# ON LINEARLY MONOTONE CURVES IN THE PROJECTIVE n-SPACE

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In previous papers [3], [4] and [5] the author has studied the connection between two classes of curves in the projective space  $R^n$ : The strictly convex curves and the linearly monotone curves. In [3] and [4] it has been proved that any plane strictly convex curve is linearly monotone and, conversely, that any linearly monotone curve is strictly convex at any ordinary point, i.e., a point belonging to an open arc of order 2. Moreover, in [5], we have shown that in  $R^n$ ,  $n \ge 3$ , any strictly convex curve is linearly monotone (Theorem 4.2, p. 228). On the following pages we shall show that, conversely, any linearly monotone curve in  $R^n$  is strictly convex at every set of n-1 points  $P_0, P_1, \ldots, P_{n-2}$  such that the osculating plane at each of these has only the point of contact in common with the (n-2)-space determined by the n-1 points. This condition is satisfied if the n-1 points belong to the same arc of order n.

In Section 1 definitions of strict convexity and linear monotonicity are given. Section 2 deals with an auxiliary theorem on plane curves, and in Section 3 we prove the theorem stated above, on linearly monotone curves in  $\mathbb{R}^n$ .

### 1. Definitions

- 1.1. By an open or closed *curve* we shall mean a topological image in  $\mathbb{R}^n$  of a segment (including the endpoints) or a circle, respectively. The curves will be assumed n times differentiable, oriented and of bounded order. (A curve is said to be of bounded order if any hyperplane has at most finitely many points in common with it.)
- 1.2. An open or closed polygon in  $R^n$ ,  $n \ge 2$ , is a sequence of segments  $P_1P_2, P_2P_3, \ldots, P_{m-1}P_m$ , resp.  $P_1P_2, P_2P_3, \ldots, P_{m-1}P_m, P_mP_1$ , its sides. The order of the polygon is said to be n, if m > n and no hyperplane has more than n points in common with it. (In case the hyperplane contains sides of the polygon, only their endpoints are counted.) In [5, p. 226-227]

Received January 1, 1963.

it was shown that an open polygon  $\Pi_n$  of order n can be changed to a closed polygon  $\overline{\Pi}_n$  of order n, and conversely, by adding, resp. removing, a suitably chosen segment.

A polygon of order n=1 is by definition a finite sequence of segments on a straight line such that two consecutive segments have only an endpoint (or both endpoints) in common whereas two non-consecutive segments have no points in common. The polygon is called closed or open according as the segments make up the whole line or a segment.

The vertices  $P_1, P_2, \ldots, P_m$  of a polygon of order 1 form a monotone sequence of points on the (projective) line. The ordered set of the vertices of a polygon of order n in the (projective)  $R^n$  is called a monotone sequence in  $R^n$  [5, p. 225].

1.3. Let a hyperplane H have the m points  $P_0, P_1, \ldots, P_{m-1}, \ m \geq n$ , in common with a curve c, the points being taken in the order determined by the parametrization of the curve. The  $chord\ P_i P_{i+1}$  is defined as that segment  $P_i P_{i+1}$  which together with the arc  $P_i P_{i+1}$  forms a closed curve of even order. The chords  $P_0 P_1, P_1 P_2, \ldots, P_{m-2} P_{m-1}$  and, if c is closed, in addition  $P_{m-1} P_0$ , form a polygon  $\Pi$  inscribed in the curve and situated in the hyperplane H. If  $\Pi$  has order n-1, the vertices  $P_0, P_1, \ldots, P_{m-1}$  form a monotone sequence in H, and the curve is called linearly monotone along the hyperplane H. The curve, as a whole, is called linearly monotone if it is linearly monotone along any hyperplane having at least n points in common with it.

For n=2 a curve which is linearly monotone along a line H determines an orientation of the line, namely by the cyclical order of the point  $P_0$ , a point  $P_0'$  of the chord  $P_0P_1$ , and the point  $P_1$ . If  $m \ge 3$ , this orientation is also determined by the monotone sequence  $P_0, P_1, \ldots, P_{m-1}$ .

With a view to an application below, we observe the following: If a line l through a point  $P_0$  on a plane curve c intersects c at a point  $P \neq P_0$  (that is, l is not a local supporting line to c at P), and if c is linearly monotone along all lines through  $P_0$  belonging to a neighbourhood of l, then c is also linearly monotone along l.

1.4. We consider a set of n-1 linearly independent points  $(P_0, P_1, \ldots, P_{n-2})$  on a curve c in  $R^n$ . The curve is called *strictly convex* at the set  $(P_0, P_1, \ldots, P_{n-2})$  if there exists at least one hyperplane H having these and no other points in common with the curve. The curve, as a whole, is called strictly convex if it is strictly convex at any set of n-1 linearly independent points (Barner [1]).

The n-1 points  $P_0, P_1, \ldots, P_{n-2}$  span a linear space  $B = B^{n-2}$ . If c is contained in an angular domain bounded by two hyperplanes through B,

then c is strictly convex at the set  $(P_0, P_1, \ldots, P_{n-2})$  since any hyperplane through B in the complementary angular domain has only the points  $P_0, P_1, \ldots, P_{n-2}$  in common with c.

#### 2. Plane curves.

2.1. Let c denote an open or closed curve in a projective plane. It is assumed to be linearly monotone along any line  $l_P$  which connects a fixed point  $P_0$  on c with a variable point  $P \neq P_0$  on c. The lines  $l_P$  are then oriented in accordance with the orientation of the curve, as described above. We denote by  $l_{P_0}$  the tangent to c at  $P_0$  oriented in accordance with the orientation of c. Let e be a conic having  $P_0$  as an interior point, and let u denote the polar of  $P_0$  with respect to e. The line  $l_P$  intersects u in a point  $U_P$  and e in two points of which we choose that point  $E_P$  for which the triple  $(P_0, E_P, U_P)$  is in accordance with the orientation of the line. The point  $E_P$  is called the point of orientation of the oriented line  $l_P$ . Without restricting the generality the conic e may be regarded as a circle with centre  $P_0$ .

To each point  $P \in c$  corresponds in this manner a point  $E_P \in c$ . The mapping  $\varphi$  of c into e thus defined is continuous. Consequently, the image  $\varphi(c)$  is closed and connected, hence a closed arc of e or the whole circle e. However, if P and Q are points on c both different from  $P_0$ , the corresponding points  $E_P$  and  $E_Q$  cannot be diametrically opposite. This implies that the image  $\varphi(c)$  is an arc contained in a semicircle, and that it cannot be a semicircle unless  $E_{P_0}$  is one if its endpoints.

If the arc  $\varphi(c)$  is smaller than a semicircle, the curve c is contained in one of the angular domains bounded by the lines joining  $P_0$  with the endpoints of  $\varphi(c)$ . Since a line through  $P_0$  in the complementary angular domain has only  $P_0$  in common with c, it follows that c is strictly convex at  $P_0$  in this case.

Now, if  $P_0$  is an ordinary point of c, that is, an interior point of a convex subarc of c, then  $E_{P_0}$  is an interior point of the arc  $\varphi(c)$ , and hence this arc is smaller than a semicircle. The lines joining  $P_0$  with the endpoints of the arc  $\varphi(c)$  are local supporting lines to c at points different from  $P_0$ . If c is open, these lines may pass through the endpoints of c.

2.2. The above result has been deduced under the assumption that c is linearly monotone along every line  $l_P$ . However, because of the fact observed at the end of 1.3, it is still true if, for a *finite* number of lines, we replace the assumption of linear monotonicity by the assumption that each of these lines *intersects* c in at least one point different from  $P_0$ .

Thus we have shown

Theorem 1. If a curve c is linearly monotone along the lines which connect an ordinary point  $P_0 \in c$  with an arbitrary other point  $P \in c$ , with the exception of at most finitely many lines which intersect the curve outside  $P_0$ , then the curve c is contained in an angular domain with  $P_0$  as vertex and, hence, is strictly convex at  $P_0$ .

2.3. If  $P_0$  is a point of inflection of c, the point  $E_{P_0}$  may be an interior point of  $\varphi(c)$ , and the above conclusion that c is strictly convex at  $P_0$  then still holds. This is also the case if  $E_{P_0}$  is an endpoint of  $\varphi(c)$  and the diametrically opposite point on e is not a point of orientation. However, it may happen that  $E_{P_0}$  is an endpoint of  $\varphi(c)$  and the diametrically opposite point is a point of orientation. Then c is not strictly convex at  $P_0$  since the lines  $l_P$  then cover the whole plane. This can only be the case if the line  $l_{P_0}$  has at least one point different from  $P_0$  in common with c and is a local supporting line to c at each of these points.

These remarks show that a curve linearly monotone as a whole is strictly convex not only at the ordinary points but in general also at the points of inflection, that is, it is strictly convex as a whole.

## 3. Curves in $\mathbb{R}^n$ , $n \geq 3$ .

3.1. Let c denote an open or closed curve in  $\mathbb{R}^n$ . We assume that c is linearly monotone along a hyperplane H, that is, there exists in H a polygon  $\Pi_{n-1}$  (or  $\overline{\Pi}_{n-1}$ ) with vertices  $P_0, P_1, \ldots, P_{m-1}, m \geq n$ , which is inscribed in c. If c is open we replace the open polygon  $\Pi_{n-1}$  by the corresponding closed polygon  $\overline{\Pi}_{n-1}$  (§ 1.2).

We consider the projection of c from a vertex  $P_i$  onto a hyperplane  $H_1$  different from H. The intersection  $H_1 \cap H$  is an (n-2)-space H'. We prove the following

Lemma. If c is linearly monotone along H, its projection c' is linearly monotone along H'.

To prove the lemma we shall show that the projection of  $\overline{\Pi}_{n-1}$  into H' is a polygon of order n-2 and inscribed in c'.

Derry [2] has shown that the projection of a closed polygon  $\bar{H}_{n-1}$  into a hyperplane from a vertex  $P_i$  is an open polygon  $\Pi'_{n-2}$  whose sides are the projections of the sides of  $\bar{\Pi}_{n-1}$ , with the exception of  $P_{i-1}P_i$  and  $P_iP_{i+1}$ . The polygon  $\Pi'_{n-2}$  may be closed without increasing its order by adding the projection  $\sigma' = P'_{i-1}P'_{i+1}$  of that segment  $\sigma = P_{i-1}P_{i+1}$ 

which together with the sides  $P_{i-1}P_i$  and  $P_iP_{i+1}$  forms a polygon (a triangle) of odd order [2, p. 51].

Since a closed curve of even order is projected onto a closed curve of even order from a point outside the curve, the sides

$$P'_0P'_1,\ldots,P'_{i-2}P'_{i-1},P'_{i+1}P'_{i+2},\ldots,P'_{m-2}P'_{m-1}$$

(and, if c is closed,  $P'_{m-1}P'_0$ ) are chords of c'. The union of the segment  $\sigma$  and the arc  $P_{i-1}P_iP_{i+1}$  is a closed curve of odd order. For, a hyperplane through a point of  $\sigma$  which intersects the chords  $P_{i-1}P_i$  and  $P_iP_{i+1}$  has an odd number of points in common with each of the corresponding arcs  $P_{i-1}P_i$  and  $P_iP_{i+1}$ . Now, a closed curve of odd order is projected onto a closed curve of even order from a point even on the curve, and consequently even0 is a chord of even1. This finishes the proof of the Lemma.

3.2. Now we assume that the curve c is linearly monotone along any hyperplane H = H(P) which connects n-1 fixed points  $P_0, P_1, \ldots, P_{n-2} \in c$  with a variable point  $P \in c$ . For any position of H the points  $P_0, P_1, \ldots, P_{n-2}$  and P are vertices of a polygon  $\Pi_{n-1}$  (or  $\overline{\Pi}_{n-1}$ ) and consequently linearly independent. The fixed points  $P_0, P_1, \ldots, P_{n-2}$  determine a (n-2)-space  $B = [P_0P_1 \ldots P_{n-2}]$ .

Let  $\alpha$  denote a plane which has only  $P_0$  in common with B. By the projection from the (n-3)-space  $[P_1,P_2,\ldots,P_{n-2}]$  onto the plane  $\alpha$  the curve c is mapped onto a curve c'. The image P' of a point P is the intersection of the (n-2)-space  $[P_1,P_2,\ldots,P_{n-2},P]$  with  $\alpha$ , and the line  $P_0P'$  is the intersection of H(P) with  $\alpha$ .

The projection of c onto c' may be decomposed into a sequence of projections from single points. First, by the projection from  $P_{n-2}$  onto the hyperplane  $[\alpha, P_1, P_2, \ldots, P_{n-3}]$  the curve c is mapped onto a curve  $c_1$ . Then this is mapped onto a curve  $c_2$  by the projection from  $P_{n-3}$  onto the subspace  $[\alpha, P_1, P_2, \ldots, P_{n-4}]$ . Continuing in this way we end up with the projection from  $P_1$  onto  $\alpha$ , by which a certain curve  $c_{n-4}$  in a 3-space is mapped onto  $c_{n-3}=c'$ .

By repeated use of the lemma it is seen that c' is linearly monotone along any line  $P_0P'$  where P' is an arbitrary point of c' which is different from  $P_0$  and from the projections  $P'_1, P'_2, \ldots, P'_{n-2}$  of the corresponding points of c. If c' is contained in an angular domain V' then c is contained in an angular domain V such that  $V' = \alpha \cap V$ .

To make the application of Theorem 1 possible we have to add assumptions in order that  $P_0$  be an ordinary point of c' and that the lines  $P_0P_i'$  for  $i=1,2,\ldots,n-2$  intersect c' at points different from  $P_0$ . These conditions will be satisfied if we assume that the osculating planes

 $\tau^2(P_i)$ ,  $i=0,1,\ldots,n-2$ , have only the point of contact in common with the (n-2)-space B. It is clear that  $P_0$  will be an ordinary point of c', and since the tangent to c' at a point  $P_i'$ ,  $i \neq 0$ , is the intersection of  $\alpha$  and the hyperplane  $[P_1P_2\ldots P_{n-2},\tau^2(P_i)]$ , it cannot pass through  $P_0$ , that is, the line  $P_0P_i'$  intersects c' at  $P_i'$ .

Using Theorem 1 we have then proved

Theorem 2. If a curve c is linearly monotone along every hyperplane which connects n-1 linearly independent points  $P_0, P_1, \ldots, P_{n-2}$  on c with an arbitrary point P on c, and the osculating planes  $\tau^2(P_i)$ ,  $i=0,1,\ldots,n-2$ , have only the point of contact in common with the (n-2)-space  $B=[P_0P_1,\ldots,P_{n-2}]$ , then c is contained in an angular domain V bounded by two hyperplanes through B and is strictly convex at the set  $(P_0,P_1,\ldots,P_{n-2})$ .

The boundary hyperplanes of V are locally supporting hyperplanes for c and pass through a tangent or, if c is an open curve, possibly through an endpoint of c.

3.3. If the n-1 points  $P_0, P_1, \ldots, P_{n-2}$  belong to the same arc  $b_n$  of order n, then the condition for the osculating planes  $\tau^2(P_i)$  is always satisfied. For, if for instance  $\tau^2(P_0)$  had other points than  $P_0$  in common with B there would exist a hyperplane through B and  $\tau^2(P_0)$  having the n-2 points  $P_1, P_2, \ldots, P_{n-2}$  and 3 coinciding points at  $P_0$  in common with  $b_n$ . But this is impossible (see [6, p. 174]).

Hence, if c as a whole is linearly monotone, it is strictly convex at any set of n-1 points belonging to the same arc of order n.

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