SOME C*-DYNAMICAL SYSTEMS WITH A SINGLE KMS STATE

DORTE OLESEN and GERT KJÆRGÅRD PEDERSEN

Introduction.

We show that a C*-dynamical system is not approximately inner, if the C*-algebra contains an isometry which is an eigenoperator for the dynamics, corresponding to a non-zero character. The simple C*untz-algebras \mathcal{O}_n , $2 \le n \le \infty$, offer examples of such dynamical systems. We show that each C*-algebra \mathcal{O}_n has exactly one KMS state φ_n . For $n < \infty$ the corresponding β -value (inverse temperature) is $\log n$. For $n = \infty$ the value for β is ∞ (i.e. φ_∞ is a ground state). These examples solve problems 11 and 13 in [11]. An example of a system with a unique invariant trace (corresponding to $\beta = 0$), but no ground states (thus not approximately inner) was given in [6].

The authors are indebted to G. A. Elliott for stimulating conversations on the subject and to S. Sakai for an inspiring series of lectures on unbounded derivations, during which these problems were brought up.

Approximately inner dynamics.

A C*-dynamical system $(\mathcal{A}, R, \varrho)$ consists of a C*-algebra \mathcal{A} and a representation ϱ of R as *-automorphisms of \mathcal{A} , such that each function $t \to \varrho_t(A)$, $A \in \mathcal{A}$, is (norm) continuous. We denote by \mathcal{A}^a the dense *-subalgebra of \mathcal{A} consisting of analytic elements. Thus $A \in \mathcal{A}^a$ if the function $t \to \varrho_t(A)$ has an extension (necessarily unique) to an entire analytic (operator-valued) function. If $0 \le \beta < \infty$ we say that an invariant state φ of \mathcal{A} is a β -KMS state if

(i)
$$\varphi(\varrho_t(A)B) = \varphi(B\varrho_{t+i\theta}(A))$$

for all t, all B in \mathcal{A} and A in \mathcal{A}^a . Note that the limit case $\beta = 0$ (chaotic state) means that φ is an invariant trace. In the other limit, $\beta = \infty$ (ground state), we modify the definition (i) to the demand that each analytic function

(ii)
$$\zeta \to \varphi(B\varrho_{\zeta}(A)), \quad A \in \mathscr{A}^{a}, B \in \mathscr{A},$$

is bounded (by ||A|| ||B||) in the upper half plane. This version of the KMS conditions differs slightly from the traditional approach. It is, however, equivalent to it (cf. [8, 8.12.13 Lemma]) and better suited to the present situation.

We say that ϱ is approximately inner if there is a net $\{H_j\}$ in \mathcal{A}_{sa} such that

(iii)
$$\|\exp(itH_i)A\exp(-itH_i)-\varrho_t(A)\|\to 0,$$

uniformly in t on compact subsets of R for each A in \mathscr{A} . It was proved in [9, Theorem 2.3] that if \mathscr{A} has a unit and ϱ is approximately inner there is a ground state for the system $(\mathscr{A}, R, \varrho)$. Moreover, by [9, Theorem 3.2], if there is an invariant finite trace on \mathscr{A} (corresponding to $\beta = 0$) there is also a β -KMS state for any $\beta > 0$. Under mild extra assumptions on ϱ (e.g. (iii) being valid for complex scalars if $A \in \mathscr{A}^a$ [8, 8.12.6], or even less, see [5] for the strongest known result) the existence of some β_0 -KMS state, $\beta_0 > 0$, will imply the existence of β -KMS states for all $\beta \ge 0$.

The condition of being approximately inner is satisfied in C*-dynamical systems of interest in C*-physics. Indeed, it is expected that every continuous one-parameter group of automorphisms of the Fermion algebra is approximately inner. Our first result put certain restrictions on the systems that are approximately inner.

THEOREM 1. Let $(\mathcal{A}, \mathbf{R}, \varrho)$ be a C*-dynamical system. If there is an isometry V in \mathcal{A} (i.e. V*V=1) which is an eigenoperator for ϱ , but not a fixed point (i.e. $\varrho_1(V) = \exp(ist)V$, $s \neq 0$), then ϱ is not approximately inner.

PROOF. Assume, to obtain a contradiction, that there is a net $\{H_j\}$ in \mathscr{A}_{sa} satisfying (iii). Let V be an isometry of \mathscr{A} such that $\varrho_t(V) = \exp(ist)V$, $s \neq 0$, and without loss of generality assume that s < 0. Adding a suitable scalar multiple of 1 to each H_j we may further assume that $H_j \geq 0$ and $0 \in \operatorname{Sp}(H_j)$ for every j. From (iii) we obtain

(iv)
$$\|\exp(itH_j)V - V\exp(it(H_j + s1))\| \rightarrow 0$$

uniformly on compact subsets of R. Since the expression in (iv) is bounded as a function of t this implies that

$$\left\| \int \left(\exp\left(itH_{j}\right)V - V\exp\left(it(H_{j} + s1)\right) \right) f(t) dt \right\|$$

$$= \|\hat{f}(H_{j})V - V\hat{f}(H_{j} + s1)\| \to 0$$

for every f in $L^1(\mathbb{R})$. Since $V^*V=1$ this gives

(v)
$$||V * \hat{f}(H_i)V - \hat{f}(H_i + s1)|| \to 0$$
.

Choose f such that $\hat{f}(s) = 1$ and supp $\hat{f} \subset]-\infty, 0[$. Then $\hat{f}(H_j) = 0$ since $H_j \ge 0$, but $\|\hat{f}(H_j + s1)\| \ge 1$ because $s \in Sp(H_j + s1)$. This contradicts (v).

The theorem above is valid in more general situations. Indeed, let G be any locally compact abelian group, and consider a C*-dynamical system $(\mathcal{A}, G, \varrho)$. We say that ϱ is approximately uniformly continuous if there is a net $\{\varrho^{(i)}\}$ of uniformly continuous representations of G in Aut (\mathcal{A}) such that

$$\|\varrho^{(j)}_{t}(A)-\varrho_{t}(A)\|\to 0$$

uniformly on compact subsets of G for each A in \mathcal{A} . In the one-parameter case this condition, although formally weaker, is equivalent to ϱ being approximately inner (cf. [8, 8.12.7 Proposition]).

THEOREM 1'. Let $(\mathcal{A}, G, \varrho)$ be a C*-dynamical system where G is connected. If there is an isometry V in \mathcal{A} such that $\varrho_t(V) = (t, \gamma)V$ for some non-zero γ in \hat{G} , then ϱ is not approximately uniformly continuous.

PROOF. By van Kampen's theorem $G = \mathbb{R}^n \times G_0$, where G_0 is compact. Write $\gamma = (\gamma_1, \gamma_0)$ with γ_1 in $\hat{\mathbb{R}}^n$ and γ_0 in \hat{G}_0 . If $\gamma_1 \neq 0$ the result follows from Theorem 1 by restricting ϱ first to \mathbb{R}^n and then further to \mathbb{R} , for a suitably chosen one-parameter subgroup of \mathbb{R}^n .

If $\gamma_1 = 0$ we may assume that G is compact. Since G is connected, \hat{G} has no elements of finite order. Thus \hat{G} can be totally ordered by a "positive" semigroup \hat{G}_+ such that

$$-\hat{G}_{+} \cap \hat{G}_{+} = \{0\}, \quad -\hat{G}_{+} \cup \hat{G}_{+} = \hat{G}$$

(see e.g. [8, 8.4.2 Lemma]). Without loss of generality we may assume that $\gamma \notin \hat{G}_+$. It follows from Arveson's theory of spectral subspaces that each uniformly continuous representation $\varrho^{(j)}$ of G in Aut (\mathscr{A}) is implemented by a uniformly continuous unitary group $\{U^{(j)}_t \mid t \in G\}$ in \mathscr{A}'' with $\operatorname{Sp}(U^{(j)}) \subset \hat{G}_+$ (see [7, Proposition 5.1] or [8, 8.5.2 Theorem]). Since $U^{(j)}$ is the minimal positive representation of G implementing $\varrho^{(j)}$, and $\operatorname{Sp}(U^{(j)})$ is finite it follows that $0 \in \operatorname{Sp}(U^{(j)})$. Now assume that $\varrho^{(j)} \to \varrho$ pointwise in norm on \mathscr{A} , and proceed to obtain a contradiction exactly as in the proof of Theorem 1.

REMARK. To each C*-dynamical system $(\mathcal{A}, G, \varrho)$ corresponds a dual system $(\mathcal{A} \not\succeq G, \hat{G}, \hat{\varrho})$ by [12, Proposition 3.1]. Here $\mathcal{A} \not\succeq G$ is the crossed product of \mathcal{A} with G and $\hat{\varrho}$ is the dual action of G on $\mathcal{A} \not\succeq G$ given by

$$\hat{\varrho}_{\gamma}(B)(t) = (t,\gamma)B(t)$$

for each continuous function $B: G \to \mathscr{A}$ with compact support (and these

elements lie dense in $\mathscr{A} \not\succeq G$). Each element t in G is embedded as a unitary multiplier U_t of $\mathscr{A} \not\succeq G$, where U_t may be regarded as a δ -function on G. It follows that $\hat{\varrho}_{\gamma}(U_t) = (t, \gamma)U_t$. From Theorem 1' we see that when \hat{G} is connected (i.e. G is torsion free), then the dual action $\hat{\varrho}$ is never approximately uniformly continuous on $\mathscr{A} \not\succeq G$.

Cuntz's C*-Algebras.

We recall some of the results from [2]. Let $2 \le n \le \infty$. Given n isometries $\{S_k\}$ on a Hilbert space \mathscr{H} such that $\sum S_k S_k^* = 1$ if $n < \infty$ and $\sum S_k S_k^* \le 1$ if $n = \infty$, we denote by \mathscr{O}_n the C*-subalgebra of $\mathscr{B}(\mathscr{H})$ generated by $\{S_k\}$. Each \mathscr{O}_n is a simple, separable C*-algebra with unit, admitting no non-zero finite (or semifinite) traces $(\mathscr{O}_n$ is a C*-algebra of type III in the language of [3]). Moreover, \mathscr{O}_n is independent of \mathscr{H} .

If $\alpha = (\alpha_1, \alpha_2, \dots, \alpha_l)$ is a multiindex of length $l = l(\alpha)$, where $1 \le \alpha_k < n+1$ for each k, we define

$$S_{\alpha} = S_{\alpha_1} S_{\alpha_2} \dots S_{\alpha_\ell}.$$

The C*-subalgebra \mathscr{F}_n of \mathscr{O}_n generated by 1 together with elements of the form $S_{\alpha}S_{\beta}^*$, where $l(\alpha) = l(\beta)$, is isomorphic to the Glimm algebra $\otimes^{\infty} M_n$ if $n < \infty$. If $n = \infty$, the algebra \mathscr{F}_{∞} is the example \mathscr{A}_N in [1] (see also [4, 4.7.17]). Thus \mathscr{F}_{∞} is primitive, but not simple, and its non-trivial closed ideals form a decreasing sequence (\mathscr{I}_n) such that

$$\mathcal{F}_{\infty}/\mathcal{I}_1 = C, \quad \mathcal{I}_n/\mathcal{I}_{n+1} = \mathcal{L}(\mathcal{H}), \quad n \in \mathbb{N}$$
.

In any case there is a unique tracial state τ_n on \mathscr{F}_n . If $n < \infty$ we have $\tau_n = \bigotimes^{\infty} (\frac{1}{n} \operatorname{Tr})$. If $n = \infty$, τ_{∞} is the complex homomorphism $\mathscr{F}_{\infty} \to \mathscr{F}_{\infty}/\mathscr{I}_1$.

The *-algebra generated algebraically by $\{S_k\}$ is denoted by \mathscr{P}_n . Each element A in \mathscr{P}_n has a unique representation.

(vi)
$$A = \sum_{k} S_{1}^{k*} A_{-k} + A_{0} + \sum_{k} A_{k} S_{1}^{k},$$

where $A_k \in \mathscr{P}_n \cap \mathscr{F}_n$ for all k in N. Moreover, $||A_k|| \le ||A||$ for every k and the map $\pi_0 \colon \mathscr{O}_n \to \mathscr{F}_n$ determined by $\pi_0(A) = A_0$ if $A \in \mathscr{P}_n$, is a projection of norm one. Note that if A and B are elements in \mathscr{P}_n represented as in (vi) then

(vii)
$$\pi_0(AB) = \sum_k S_1^{k*} A_{-k} B_k S_1^k + A_0 B_0 + \sum_k A_k S_1^k S_1^{k*} B_{-k}.$$

LEMMA 1. (cf. [2, 1.10. Proof of Proposition]). For each point e^{it} on the circle T define $\varrho_t(S_k) = e^{it}S_k$ for all k. Then ϱ_t has a unique extension to a *-automorphism of \mathcal{O}_n , and we obtain a C*-dynamical system $(\mathcal{O}_n, T, \varrho)$. Moreover, \mathscr{F}_n is the fixed-point algebra of ϱ in \mathcal{O}_n and $\mathscr{P}_n \subset (\mathcal{O}_n)^a$.

PROOF. The only choice of $\varrho_t(A)$, if $A \in \mathcal{P}_n$ represented as in (vi) is

(viii)
$$\varrho_{t}(A) = \sum_{k} e^{-ikt} S_{1}^{k*} A_{-k} + A_{0} + \sum_{k} e^{ikt} A_{k} S_{1}^{k}$$

With this definition ϱ_t becomes a linear *-preserving continuous map of \mathscr{P}_n onto itself with inverse ϱ_{-t} . Take A, B in \mathscr{P}_n represented as in (vi), and show by straightforward computations that $\varrho_t(AB) = \varrho_t(A)\varrho_t(B)$. Thus each ϱ_t is a *-automorphism of \mathscr{P}_n and extends by continuity to a *-automorphism ϱ_t of \mathscr{O}_n .

Clearly the function $t \to \varrho_t$ is a representation of T (identified with $R/2\pi Z$) in Aut (\mathcal{O}_n) . Moreover, since $||A_k|| \le ||A||$ for all k and each A in \mathcal{P}_n , it follows from the expression (viii) that $t \to \varrho_t(A)$ is continuous for each A in \mathcal{P}_n , and therefore also for each A in \mathcal{O}_n . Thus $(\mathcal{O}_n, T, \varrho)$ is a C*-dynamical system.

If $B \in \mathscr{P}_n \cap \mathscr{F}_n$ then B is a fixed-point for ϱ . By continuity $\mathscr{F}_n \subset (\mathscr{O}_n)^{\varrho}$. Conversely, if $B \in (\mathscr{O}_n)^{\varrho}$, take $\varepsilon > 0$ and choose A in \mathscr{P}_n such that $||B - A|| < \varepsilon$. Using the expression (viii) we get

$$\|B-A_0\| = \left\|\int_{\mathbb{T}} \varrho_t(B-A) dt\right\| \leq \|B-A\| < \varepsilon.$$

Since ε is arbitrary it follows that $B \in \mathscr{F}_n$. Finally, from the expression (viii) it is immediate that every A in \mathscr{P}_n is analytic for ϱ , i.e. $\mathscr{P}_n \subset (\mathscr{O}_n)^a$.

LEMMA 2. Let $\pi_0: \mathcal{O}_n \to \mathcal{F}_n$ be the projection of norm one mentioned above. If τ_n is the unique tracial state on \mathcal{F}_n , define $\varphi_n = \tau_n \circ \pi_0$ on \mathcal{O}_n . The state φ_n satisfies the equations:

(ix)
$$\varphi_n(S_1AS_1^*) = n^{-1}\varphi_n(A), \quad A \in \mathcal{O}_n \quad (with \infty^{-1} = 0);$$

(x)
$$\varphi_n(S_1^{k*}AS_1^k) = n^k \varphi_n(E_k A E_k), \quad A \in \mathcal{O}_n,$$

where $E_k = S_1^k S_1^{k*}$ and $n < \infty$.

PROOF. Since τ_n is a trace on \mathscr{F}_n we have for all A, B in \mathscr{F}_n

$$\tau_n(S_1ABS_1^*) = \tau_n((S_1AS_1^*)(S_1BS_1^*)) = \tau_n(S_1BAS_1^*).$$

Thus $\tau_n(S_1 \cdot S_1^*)$ is also a trace on \mathscr{F}_n , and the unicity of τ_n implies that $\tau_n(S_1 \cdot S_1^*) = \tau_n(S_1 S_1^*) \tau_n(\cdot)$. However, each element $V_k = S_1 S_k^*$ is a partial isometry in \mathscr{F}_n with

$$V_k V_k^* = S_1 S_1^*, \quad V_k^* V_k = S_k S_k^*.$$

If $n < \infty$ this implies that

$$1 = \sum \tau_n(S_k S_k^*) = n \tau_n(S_1 S_1^*) ,$$

whence $\tau_n(S_1S_1^*) = n^{-1}$. If $n = \infty$ the same reasoning gives $\tau_n(S_1S_1^*) = 0$. In both cases we have (ix).

Assume now that $n < \infty$. Applying (ix) successively we obtain (x) since

$$\varphi_n(S_1^k * A S_1^k) = n\varphi_n(S_1 S_1^k * A S_1^k S_1^*)$$

$$= \dots = n^k \varphi_n(S_1^k S_1^k * A S_1^k S_1^*) = n^k \varphi_n(E_k A E_k).$$

PROPOSITION. Consider the C*-dynamical system $(\mathcal{O}_n, T, \varrho)$ defined in Lemma 1 and let φ_n be the invariant state of \mathcal{O}_n defined in Lemma 2. Then φ_n satisfies the KMS condition at $\beta = \log n$ if $n < \infty$, and φ_∞ is a ground state (i.e. $\beta = \infty$) for \mathcal{O}_∞ .

PROOF. Assume first that $n < \infty$. Take A, B in \mathcal{P}_n , represented as in (vi). Since this representation is unique we have $E_k A_{-k} = A_{-k}$ and $A_k E_k = A_k$ for all k > 0, where $E_k = S_k^1 S_k^{1*}$. Thus by (vii) and (x) we get

$$\varphi_n(AB) = \tau_n \left(\sum_k S_1^{k*} A_{-k} B_k S_1^k + A_0 B_0 + \sum_k A_k E_k B_{-k} \right)$$

$$= \sum_k n^k \tau_n (A_{-k} B_k) + \tau_n (A_0 B_0) + \sum_k \tau_n (A_k B_{-k}).$$

Put $\zeta = i \log n$. Since $\varrho_t(S_1) = e^{it}S_1$ it follows that $\varrho_{\zeta}(S_1) = n^{-1}S_1$ and $\varrho_{\zeta}(S_1^*) = nS_1^*$. Thus by (vii) and (x) we get

$$\varphi_n(B\varrho_{\zeta}(A)) = \tau_n \left(\sum_k S_1^{k*} B_{-k} A_k n^{-k} S_1^{k} + B_0 A_0 + \sum_k B_k S_1^{k} n^k S_1^{k*} A_{-k} \right)$$

$$= \sum_k \tau_n(B_{-k} A_k) + \tau_n(B_0 A_0) + \sum_k n^k \tau_n(B_k A_{-k}).$$

Since τ_n is a trace on \mathscr{F}_n we see from these results that $\varphi_n(AB) = \varphi_n(B\varrho_{\zeta}(A))$. Replacing A with $\varrho_t(A)$ we get

$$\varphi_n(\varrho_t(A)B) = \varphi_n(B\varrho_{t+i\log n}(A))$$
.

Since \mathcal{P}_n is dense in $(\mathcal{O}_n)^a$ it follows that the equation above is valid for any A in $(\mathcal{O}_n)^a$ and B in \mathcal{O}_n , so that φ_n is a $\log n - KMS$ state.

If $n = \infty$, we know from (ix) that $\tau_{\infty}(E_k) = 0$ for every k. Consequently, for A, B in \mathcal{P}_n and $\zeta = t + is$ we have

$$\begin{split} & \varphi_{\infty}(B \varrho_{\zeta}(A)) \\ & = \tau_{\infty} \left(\sum_{k} S_{1}^{k*} B_{-k} A_{k} e^{ik\zeta} S_{1}^{k} + B_{0} A_{0} + \sum_{k} B_{k} S_{1}^{k} e^{-ik\zeta} S_{1}^{k*} A_{-k} \right) \end{split}$$

$$= \tau_{\infty} \left(\sum_{k} e^{ik\zeta} S_{1}^{k*} B_{-k} A_{k} S_{1}^{k} + B_{0} A_{0} + \sum_{k} e^{-ik\zeta} B_{k} E_{k} A_{-k} \right)$$

$$= \sum_{k} e^{ikt} e^{-ks} \tau_{\infty} \left(S_{1}^{k*} B_{-k} A_{k} S_{1}^{k} \right) + \tau_{\infty} \left(B_{0} A_{0} \right) .$$

Thus the function $\zeta \to \varphi_{\infty}(B\varrho_{\zeta}(A))$ is bounded in the upper half plane. By the Phragmen-Lindelöf theorem the supremum of the function in the region is the supremum on the real line, i.e.

$$|\varphi_{\infty}(B\varrho_{r}(A))| \leq ||B|| ||A||.$$

Another application of the Phragmen-Lindelöf theorem shows that each function $\zeta \to \varphi_{\infty}(B\varrho_{\zeta}(A))$ is bounded in the upper half plane for every B in \mathcal{O}_{∞} and A in $(\mathcal{O}_{\infty})^a$; i.e., φ_{∞} is a ground state for \mathcal{O}_{∞} .

THEOREM 2. Let $2 \le n \le \infty$. The C*-dynamical system $(\mathcal{O}_n, \mathsf{T}, \varrho)$ defined in Lemma 1 has exactly one KMS state (viz. φ_n). The only admissible β -value is $\log n$ if $n < \infty$ and ∞ if $n = \infty$.

PROOF. Assume first that $n < \infty$. From the Proposition we know that φ_n is a KMS state corresponding to $\beta = \log n$. Assume now that φ is a β -KMS state for some β ($0 \le \beta \le \infty$). If $\beta < \infty$ this implies that φ is a trace on \mathscr{F}_n (cf. (i)), whence $\varphi = \varphi_n$ by the unicity of τ_n . If $\beta = \infty$ we take $\zeta = t + is$ and compute

$$\varphi(S_k \varrho_{\ell}(S_k^*)) = e^{-i\zeta} \varphi(S_k S_k^*) = e^{-it} e^s \varphi(S_k S_k^*).$$

The function $\zeta \to \varphi(S_k \varrho_{\zeta}(S_k^*))$ is not bounded in the upper half plane unless $\varphi(S_k S_k^*) = 0$. But $\sum S_k S_k^* = 1$ and $\varphi(1) = 1$, a contradiction. Thus $\beta = \log n$ is the only admissible value.

In the case $n=\infty$ we know from the Proposition that φ_{∞} is a ground state for \mathscr{O}_{∞} . Assume now that φ is a β -KMS state for some β $(0 \le \beta \le \infty)$. If $\beta < \infty$ this gives

$$\varphi(S_k S_k^*) = \varphi(S_k^* \varrho_{i\beta}(S_k)) = e^{-\beta} \varphi(S_k^* S_k) = e^{-\beta}.$$

However, $\sum S_k S_k^* \le 1$ so we have a contradiction. If $\beta = \infty$ we see from (xi) that $\varphi(S_k S_k^*) = 0$ for all k. By the Cauchy-Schwarz inequality this implies that $\varphi(S_\alpha S_\beta^*) = 0$ for all multiindices α, β (with $l(\alpha) = l(\beta)$) unless $l(\alpha) = l(\beta) = 0$. But the elements $S_\alpha S_\beta^*$, $1 \le l(\alpha) = l(\beta)$, generate the maximal ideal \mathscr{I}_1 in \mathscr{F}_∞ and $\mathscr{F}_\infty/\mathscr{I}_1 = \mathbb{C}$. Consequently $\varphi = \varphi_\infty$.

REFERENCES

- H. Behncke, F. Krauss and H. Leptin, C*-algebren mit geordneten Ideal Folgen, J. Functional Analysis 10 (1972), 204-211.
- 2. J. Cuntz, Simple C*-algebras generated by isometries, Comm. Math. Phys. 57 (1977), 173-185.
- 3. J. Cuntz and G. K. Pedersen, Equivalence and traces on C*-algebras, J. Functional Analysis (to appear).
- J. Dixmier, Les C*-algèbres et leurs représentations (Cahiers Scientifiques 29), Gauthier-Villars, Paris, 1964.
- P. E. T. Jørgensen, Trace states and KMS states for approximately inner dynamical oneparameter groups of *-automorphisms, Comm. Math. Phys. 53 (1977), 135-142.
- E. C. Lance and A. Niknam, Unbounded derivations of group C*-algebras, Proc. Amer. Math. Soc. 61 (1976), 310-314.
- 7. D. Qlesen, On norm-continuity and compactness of spectrum, Math. Scand. 35 (1974), 223-236.
- 8. G. K. Pedersen, C*-algebras and their automorphism groups, Academic Press (to appear).
- 9. R. T. Powers and S. Sakai, Existence of ground states and KMS states for approximately inner dynamics, Comm. Math. Phys. 39 (1975), 273-288.
- 10. W. Rudin, Real and complex analysis, McGraw-Hill, New York, 1966.
- 11. S. Sakai, Recent developments in the theory of unbounded derivations in C*-algebras, in Proceedings of the US-Japan seminar on C*-algebras and their application to theoretical physics, April 1977, U.C.L.A.
- 12. H. Takai, On a duality for crossed products of C*-algebras, J. Functional Analysis 19 (1975), 23-39.

MATEMATISK INSTITUT
KØBENHAVNS UNIVERSITET
UNIVERSITETSPARKEN 5
DK-2100 KØBENHAVN Ø
DANMARK